
^8He STRUCTURE WITHIN A THREE-CLUSTER MICROSCOPIC MODEL

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The structure of ^8He is investigated within a three-cluster microscopic model. The three-cluster configuration $\alpha + ^2\text{n} + ^2\text{n}$ was used to describe the properties of the ground state of the nucleus. The obtained results evidently indicate the existence of a neutron halo in ^8He .

Introduction

The development of the experimental technique made it possible to investigate light nuclei with large neutron excess, i.e., the nuclei for which the ratio $\eta = (N - Z)/A$ is significantly larger than for common ones. Such nuclei lie near the drip line and are β -unstable. They live a short time and transform into nuclei with approximately equal number of protons and neutrons by emitting electrons. A number of unexpected properties were discovered in those nuclei, for instance, a neutron halo. It is natural that many attempts were undertaken to explain those properties within microscopic and semi-microscopic methods [1 - 8].

Our aim is to investigate the structure of the ^8He ground state. It is interesting that ^8He has the largest value of $\eta = 0.5$ among other nucleon-stable nuclei. Note that the average values of $\eta = 0.4$ for nuclei near the neutron drip line. As early as in 1960, Ya.B.Zeldovich [9] and V.I.Goldansky [10] indicated a possibility of the existence of ^8He isotope. It was experimentally confirmed [11] in the middle of sixties. The subsequent analysis shows that the lowest threshold of ^8He decay is $^6\text{He} + 2\text{n}$ and lies by 2.1 MeV above the ground state and energy of the threshold $\alpha + 4\text{n}$ equals 3.10 MeV (see, for instance, [12]).

The most complete information on light nuclei with neutron excess can be obtained with a microscopic model. In this case, the problem is connected with solving the many-particle Schrödinger equation with a fixed

(chosen) nucleon-nucleon interaction. The equation has to be solved with some simplification based on one or other physical considerations. The Resonating Group Method [13] or its Algebraic Version [14, 15] is one of such methods.

In this paper, we make use of the Algebraic Version of the Resonating Group Method in which ^8He is considered as a three-cluster configuration $\alpha + ^2\text{n} + ^2\text{n}$. It is obvious that we make *a priori* some assumptions on the structure of the nucleus. First, the wave functions of each cluster are modelled by shell-model functions. Second, valent neutrons unite in dineutron clusters. As a justification for such an assumption can be served the fact, indicated by A.B.Migdal [16], that the interaction between two neutrons may be increased significantly in the presence of the third particle (nucleus). It can give rise to the creation of the dineutron clusters on the surface of a nucleus. The chosen clusterization allows us to consider α -particle as a core, despite that the lowest threshold of ^8He decay is $^6\text{He} + \text{n} + \text{n}$. Earlier, A.A.Ogloblin [17] indicated the importance of the cluster configuration $\alpha + ^2\text{n} + ^2\text{n}$. He pointed out that the bound energy of two neutrons in ^8He is two times larger than that in ^6He . This fact led him to the conclusion that ^6He cannot serve as a core and the neutron halo in ^8He has to be consisted of four neutrons.

Note also that the usage of dineutron clusters is a quite grounded approximation. For example, in [18], dineutron and also diproton clusters were successfully used to describe exit channels of the reactions $^3\text{H} + ^3\text{H} \rightarrow ^4\text{He} + \text{n} + \text{n}$ and $^3\text{He} + ^3\text{He} \rightarrow ^4\text{He} + \text{p} + \text{p}$, respectively. Besides, in [19], main features of ^{11}Li were reproduced within the cluster configuration $^9\text{Li} + ^2\text{n}$ with a pointless dineutron.

Method

The present method for investigation of the ⁸He ground state is based on the Algebraic Version of the Resonating Group Method (AV RGM). For a long time, this version was used for studying the bound states of two-cluster systems, reactions with a few open channels, interaction of these channels with collective monopole and quadrupole modes, and also processes of full disintegration of light nuclei [20 - 22]. Recently, the AV RGM was actively applied to describe three-cluster systems [23 - 26].

The AV RGM is based on the usage of an oscillator basis for solving bound state problems and problems of continuous spectrum states. This is achieved by expanding a wave function of inter-cluster motion in the oscillator basis. As a result, a trial three-cluster function takes the form

$$\Psi(A) = \sum_n C_n \hat{A} [\Phi_1(A_1) \Phi_2(A_2) \Phi_3(A_3) f_n(\mathbf{q}_1, \mathbf{q}_2)], \tag{1}$$

where \hat{A} is the antisymmetrization operator, $\Phi_i(A_i)$ are the internal functions of the cluster, which are selected in one or other form prior to solving the problem (for instance, in the form of many-particle oscillator shell functions, as in our case); the set of coefficients C_n is nothing else but a wave function in the oscillator representation. This function should be obtained from a system of linear equations:

$$\sum_{n'} [\langle n, | \hat{H} | n' \rangle - E \langle n | n' \rangle] C_{n'} = 0,$$

which is derived directly from the many-particle Schrödinger equation. The oscillator functions $f_n(\mathbf{q}_1, \mathbf{q}_2)$, where \mathbf{q}_1 and \mathbf{q}_2 are Jacobi vectors fixing a position of clusters in space, are determined in a six-dimensional space and constitute the irreducible representation [N00] of the unitary group $U(6)$. Thus, the composite index n consists of indices (six in total) of the irreducible representation of the $U(6)$ group and its subgroups.

The choice of one or other reductions of the $U(6)$ group is dictated by considerations of physical lucidity and simplicity of numerical realizations as well. To consider the bound state problem, it is convenient to use bases, whose classification is connected with the following reduction of the $U(6)$ group:

$$U(6) \supset U(3) \otimes U(3) \rightarrow |N_1, l_1, N_2, l_2, LM\rangle$$

$$\cup \quad \cup$$

$$SO(3) \otimes SO(3) \supset SO(3)$$

$$U(6) \supset SU(3) \otimes U(2) \rightarrow |(\lambda\mu) v, \omega LM\rangle$$

$$\cup \quad \cup$$

$$SO(3) \quad O(3)$$

The first basis is usually called the basis of two uncoupled oscillators or bioscillator basis (BO). Each of the $SU(3)$ groups, associated with one of the Jacobi vectors \mathbf{q}_1 and \mathbf{q}_2 , generates the quantum numbers N_1, l_1 and N_2, l_2 . They are the principal quantum number (or the number of oscillator quanta) and partial angular momentum along the respective Jacobi vector.

The second basis is an ' $SU(3)$ ' basis. Wave functions of this basis are classified through the well-known Elliott indices (λ, μ) of the $SU(3)$ group, multiplicity index ω arising in the reduction $SU(3) \subset SO(3)$, and quantum number $v = \frac{1}{2}(N_1 - N_2)$ connected with oscillator quanta along the Jacobi vectors \mathbf{q}_1 and \mathbf{q}_2 .

The total number of oscillator quanta equals $N = N_1 + N_2 = \lambda + 2\mu$ and defines the irreducible representation of the $U(6)$ group. For a given N , i.e., for a fixed oscillator shell, functions of both bases are related to each other through a unitary transformation, because these bases are eigenfunctions of the same oscillator Hamiltonian in the six-dimensional space. Thus, they are equivalent.

However, we make use of two bases. This is because the bioscillator basis has more natural quantum numbers. Meanwhile, the $SU(3)$ basis is more convenient for numerical implementation, in particular, for eliminating Pauli forbidden states. Besides, the usage of two bases gives additional information on optimal subspaces, which allow one to obtain reliable results with minimal effort.

The elimination of Pauli forbidden states is performed by diagonalization of the matrix of the anisymmetrization operator

$$||\langle n | n' \rangle||, \tag{2}$$

calculated between the basis functions (1). Pauli forbidden states correspond to those eigenvalues of the matrix $||\langle n | n' \rangle|| = ||\langle n | \hat{A} | n' \rangle||$ which have zero eigenvalues. Pauli allowed states are a combination (composition) of original basis functions of a given oscillator shell which are eigenfunctions of the antisymmetrization operator.

In this connection the original scheme of classification is totally changed for the bioscillator basis, but the quantum numbers $(\lambda\mu)$ are preserved for the $SU(3)$ basis, because the matrix $||\langle n | n' \rangle||$ is off-diagonal with respect to the quantum number v only.

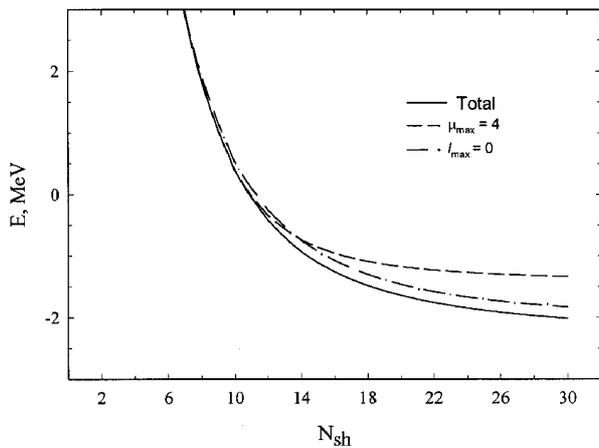


Fig. 1. ^8He ground state energy as a function of the number N of oscillator shells involved in the calculation

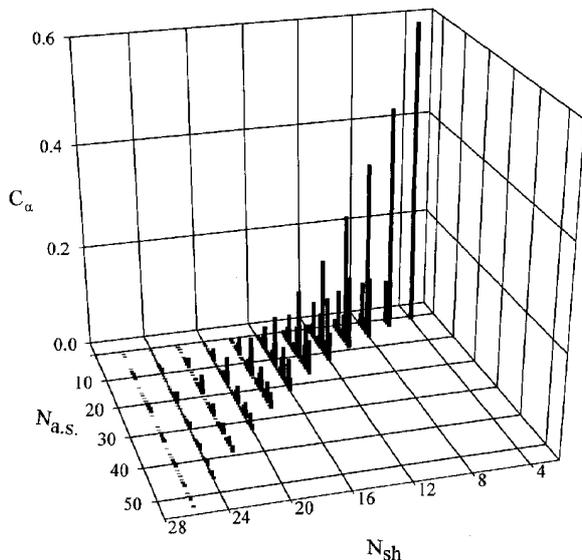


Fig. 2. Wave function of the ^8He ground state in the oscillator representation

Results

The results, represented in this section, were obtained with the Volkov potential [27]. The only free parameter, oscillator radius r_0 , was chosen to minimize the threshold energy of the ^8He decay into ^4He and two dineutrons. It turns out to be 1.51 fm. Under such conditions, the energy of the $^4\text{He} + ^2\text{n} + ^2\text{n}$ threshold equals -22.15 MeV and the bound state energy of α -particle is -26.84 MeV. Coulomb interaction was neglected because it leads to a shift of the bound state energy and threshold energy by the same value.

In what follows, we use two different trees of Jacobi vectors. In the first tree which we call T -tree, the vector \mathbf{q}_1 defines the distance between two dineutrons, and the vector \mathbf{q}_2 fixes the distance between the center of mass of two dineutrons and α -particle. The second tree is called Y -tree. In this tree, the first vector \mathbf{q}_1 determines the distance between α -particle and one of the dineutrons, and the second vector \mathbf{q}_2 is connected with the distance between the second dineutron and center of mass of the first dineutron and α -particle.

The ground state of ^8He is considered with the basis which involves all oscillator functions of 15 lowest oscillator shells, i.e., basis functions with even values of the principal quantum number N up to $N = 30$. The total number of original basis functions equals 815 and the total number of Pauli allowed states reduces to 399 functions. Such amount of basis functions provides a fairly good convergence of the bound state energy, as is demonstrated in Fig. 1. In this figure, we display the ground state energy as a function of the principal quantum number N . The energy is counted from the threshold $\alpha + ^2\text{n} + ^2\text{n}$. In Fig. 1, we also display the ground state energy obtained with some subspaces of the total space of the oscillator basis used. In the BO basis, such a subspace is defined by the maximal value of the partial angular momentum $l = 0$, while, for $SU(3)$ -basis, such a subspace involves basis functions with $\mu \leq 4$. The later subspace consisting of 274 functions gives the energy which noticeably differs from 'exact' one, obtained with the total basis. But, with the former subspace including only 118 functions, we obtain the energy which is very close to the 'exact' value. This is probably connected with that the interaction between clusters is most strong in the S -state.

In Fig. 2, we display the wave function of the ^8He ground state, more exactly, the coefficients C_α of the expansion over Pauli allowed states. Two labels N_{sh} and $N_{a.s.}$ are used to classify Pauli allowed functions ($\alpha = \{N_{sh}, N_{a.s.}\}$). The first label N_{sh} numerates oscillator shells and the second one, $N_{a.s.}$, numerates Pauli allowed states of a given oscillator shell. The expansion coefficients C_α were determined in the $SU(3)$ -basis, where the indices $(\lambda\mu)$ are good quantum numbers after eliminating Pauli forbidden states. The detailed analysis shows that the main contribution (around 80%) to the wave function comes from the basis states with $\mu = 2$, while the basis states with $\mu = 0$ give only 9%. Note that the former states in ^6He (see [23, 24]) were a dominated subspace with the contribution of more than 93%.

It is seen from Fig. 2 and more clearly from Fig. 3 (where the weights of different oscillator shells are displayed) that the main contribution comes from the lowest oscillator shells, however the contribution of

shells with large N is also noticeable. It indicates a substantial clusterization of the nuclei, i.e., for a large amount of time, valent neutrons move far from the α -particle, making a neutron halo.

In order to obtain additional information on the role of different subspaces of the total space of oscillator functions, we impose various restrictions on the quantum numbers of basis states. First, for the bioscillator basis, we took a subspace with the maximal value of partial angular momenta ($l = l_1 = l_2$) $l = 0$, $l = 2$ and $l = 4$. It was made for both the Y - and T -trees of Jacobi vectors. For the $SU(3)$ -basis, we used only the T -tree, and the restriction was imposed on the maximal value of $\mu = 0, 2$ and 4 . Results of such calculations are presented in Tab.1.

In Tab. 2, we compare the calculated mass, neutron and proton root-mean-square (RMS) radii with available experimental data. The theoretical values of RMS radii are a little larger than experimental ones which we took from [28] and [29]. This is perhaps because the calculated binding energy is a little less than the experimental one. But the present model correctly reproduces the general picture of ⁸He. These

Table 1. Ground state energy of ⁸He counted from the ⁴He + ²n + ²n threshold

Basis	Jacobi tree	Subspace	E , MeV	Number of functions
BO	T	Total	-2.065	399
		$l = 0$	-1.832	118
		$l \leq 2$	-2.047	219
		$l \leq 4$	-2.064	293
BO	Y	Total	-2.065	399
		$l = 0$	-1.839	118
		$l \leq 2$	-2.065	219
		$l \leq 4$	-2.065	219
SU(3)	T	Total	-2.065	399
		$\mu = 0$	6.341	91
		$\mu \leq 2$	0.172	196
		$\mu \leq 4$	-1.335	274

Table 2. Root mean square radii for the ground state of ⁸He

RMS, fm	Theory	Experiment [28]	Experiment [29]
RMSm	2.73	2.37 ± 0.18	2.52 ± 0.03
RMSp	2.08	1.89 ± 0.17	2.15 ± 0.02
RMSn	2.91	2.50 ± 0.19	2.64 ± 0.03
RMSn - RMSp	0.84	0.61	0.49

Table 3. Root mean square radii of ⁸He, obtained by different methods

RMS, fm	AV RGM	RRGM [1]	Shell Model [4]
RMSm	2.73	2.41	1.684
RMSp	2.08	1.71	
RMSn	2.91		

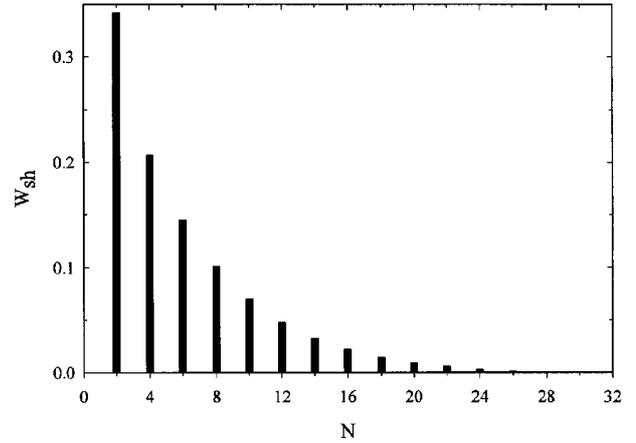


Fig. 3. Contribution of different oscillator shells N to the wave function of the ⁸He ground state

results also indicate the existence of a neutron halo in the nucleus.

In Tab. 3, we collected the mass, neutron and proton RMS radii, obtained with different theoretical methods: AV RGM (present calculations), the Refined Resonating Group Method (RRGM) [1], and Multiconfiguration Shell Model [4].

Having calculated the coefficients C_n , a wave function in the oscillator representation, we thus obtain the wave function for relative motion of the three-cluster system:

$$\Phi(\mathbf{q}_1, \mathbf{q}_2) = \sum_n C_n \phi_n(\mathbf{q}_1, \mathbf{q}_2). \quad (3)$$

By using (3), we can evaluate the mean distance between clusters. To this end, one has to calculate the quantities

$$Q_i^2 = \int d\mathbf{q}_1 d\mathbf{q}_2 \Phi^*(\mathbf{q}_1, \mathbf{q}_2) \mathbf{q}_i^2 \Phi(\mathbf{q}_1, \mathbf{q}_2),$$

which, within the regard for the normalization of the wave function and definition of Jacobi coordinates, define the sought parameters. For instance, for the T -tree, the mean value of q_1 is connected with the base of an isosceles triangle and the mean value of q_2 is connected with its height.

The mean distance between two dineutrons turns out to be 2.33 fm and the mean distance between α -particle and the center of mass of two dineutrons is 1.42 fm. Thus, in ⁸He, three clusters form an obtuse isosceles triangle with α -particle at the vertex of the obtuse angle.

Note, that the situation is somewhat different for ⁶He. Cluster form a rectangular triangle. Two valent neutrons in the presence of α -particle make a

subsystem with the RMS radius equal to 2.52 fm which is less than the RMS radius of a free deuteron (2.69 fm) calculated with the same potential and the same number of basis functions.

The difference in the geometry of cluster's disposition in ${}^6\text{He}$ and ${}^8\text{He}$ is more likely connected with the Pauli principle. There is an effective repulsion between two dineutrons, arising from the Pauli principle, which places dineutrons on different sides the α -particle. Contrary to the case of ${}^8\text{He}$, valent neutrons with opposite orientations of spins may unite in a rather compact subsystem in ${}^6\text{He}$ (due to the presence of α -particle).

Conclusion

In this paper, we have investigated the ground state properties of ${}^8\text{He}$ within the three-cluster microscopic model. The three-cluster configuration ${}^4\text{He} + {}^2\text{n} + {}^2\text{n}$ was used to simulate the dynamics of the eight-nucleon system. The model suggested describes reasonably well the parameters of the ground state: binding energy, mass, proton and neutron root mean square radii. The analysis of the system shows that valent neutrons move at a large distance from α -particle, forming a neutron halo in ${}^8\text{He}$.

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